

Code: 20ME2702B

IV B.Tech - I Semester – Regular Examinations - DECEMBER 2023

ROBOTICS

(Common for ALL BRANCHES)

Duration: 3 hours

Max. Marks: 70

Note: 1. This paper contains questions from 5 units of Syllabus. Each unit carries 14 marks and have an internal choice of Questions.

2. All parts of Question must be answered in one place.

BL – Blooms Level

CO – Course Outcome

| | | | BL | CO | Max. Marks |
|----------------|---|--|----|-----|------------|
| UNIT-I | | | | | |
| 1 | What are the major components of Robot? Explain them briefly with neat sketch. | | L2 | CO1 | 14 M |
| OR | | | | | |
| 2 | a) | What is work envelope? Draw work envelope for Cartesian coordinate, cylindrical coordinate and spherical coordinate. | L2 | CO1 | 8 M |
| | b) | How do you select a robot? List various selection criteria's of robots. | L2 | CO1 | 6 M |
| UNIT-II | | | | | |
| 3 | Discuss the types of hydraulic actuators. Explain them with neat sketch. | | L2 | CO2 | 14 M |

OR

| | | | | | |
|---|----|---|----|-----|-----|
| 4 | a) | Compare different types of end effectors based on its applications. | L2 | CO2 | 8 M |
| | b) | Write short note on any one electrical actuator. | L2 | CO2 | 6 M |

UNIT-III

| | | | | | |
|---|--|---|----|-----|------|
| 5 | | Explain in detail about various programming languages used in Robotics. | L2 | CO3 | 14 M |
|---|--|---|----|-----|------|

OR

| | | | | | |
|---|--|---|----|-----|------|
| 6 | | What is lead through robot programming? Compare it with Teach pendent method. | L2 | CO3 | 14 M |
|---|--|---|----|-----|------|

UNIT-IV

| | | | | | |
|---|----|--|----|-----|-----|
| 7 | a) | Classify the types of sensors used in robots and discuss them in detail. | L1 | CO4 | 7 M |
| | b) | Explain about any one displacement sensor with neat sketch. | L2 | CO4 | 7 M |

OR

| | | | | | |
|---|--|---|----|-----|------|
| 8 | | Compare different type of Acoustic sensors based on its applications. | L3 | CO4 | 14 M |
|---|--|---|----|-----|------|

UNIT-V

| | | | | | |
|---|--|--|----|-----|------|
| 9 | | Explain in detail about the robot real time applications in material handling. | L2 | CO4 | 14 M |
|---|--|--|----|-----|------|

OR

| | | | | |
|----|---|----|-----|------|
| 10 | Explain in detail about the applications of robot in processing operations. | L2 | CO4 | 14 M |
|----|---|----|-----|------|